

Exercícios: 7, 10, 11, 13, 15, 16 : French cap. 4

$$\textcircled{7} \quad \ddot{x} + 2\gamma\dot{x} + \omega_0^2 x = \frac{F_0}{m} \cos(\omega t) \Rightarrow x(t) = \frac{F_0}{m} \frac{\cos(\omega t + \varphi)}{\sqrt{(\omega_0^2 - \omega^2)^2 + (2\gamma\omega)^2}}$$

(a) Energia cinética instantânea?

$$E_c = \frac{1}{2} m \dot{x}^2, \quad \dot{x}(t) = -\frac{F_0 \omega}{m} \frac{\sin(\omega t + \varphi)}{[(\omega_0^2 - \omega^2)^2 + (2\gamma\omega)^2]^{1/2}}$$

$$\therefore E_c = \frac{1}{2} m \left(\frac{F_0 \omega}{m}\right)^2 \frac{\sin^2(\omega t + \varphi)}{[(\omega_0^2 - \omega^2)^2 + (2\gamma\omega)^2]}$$

(b) Energia potencial instantânea?  $\omega_0^2 = k/m$

$$E_p = \frac{1}{2} K x^2 = \frac{1}{2} m \omega_0^2 \left(\frac{F_0}{m}\right)^2 \frac{\cos^2(\omega t + \varphi)}{[(\omega_0^2 - \omega^2)^2 + (2\gamma\omega)^2]}$$

(c)  $\langle f \rangle = \frac{1}{T} \int_0^T f(t) dt$

$$\langle E_c \rangle = \frac{1}{T} \int_0^T \frac{1}{2} m \left(\frac{F_0 \omega}{m}\right)^2 \frac{\sin^2(\omega t + \varphi)}{[(\omega_0^2 - \omega^2)^2 + (2\gamma\omega)^2]} dt$$

$$\cos 2x = \cos^2 x - \sin^2 x = 1 - 2\sin^2 x \Rightarrow \sin^2 x = \frac{1 - \cos(2x)}{2}$$

$$\langle E_c \rangle = \frac{1}{T} \int_0^T \frac{1}{2} m \frac{F_0^2 \omega^2}{m^2} \frac{1}{[(\omega_0^2 - \omega^2)^2 + (2\gamma\omega)^2]} \left(\frac{1 - \cos(2\omega t + 2\varphi)}{2}\right) dt$$

$$\begin{aligned}
\langle E_c \rangle &= \frac{1}{T} \frac{1}{2} m \left( \frac{F_0 \omega}{m} \right)^2 A^2(\omega) \int_0^T \left( \frac{1}{2} - \frac{\cos(2\omega t + 2\varphi)}{2} \right) dt \\
&= (\dots) \left[ \frac{1}{2} - \frac{1}{2} \int_{2\varphi}^{2\omega T + 2\varphi} \cos u \frac{du}{2\omega} \right] = (\dots) \left[ \frac{1}{2} - \frac{1}{2(2\omega)} \sin(2\omega t + 2\varphi) \Big|_0^T \right] \\
&= (\dots) \left[ \frac{1}{2} - \frac{1}{4\omega} \left( \sin(2\omega T + 2\varphi) - \sin(2\varphi) \right) \right] \\
&= (\dots) \left[ \frac{1}{2} - \frac{1}{4\omega} \left( \sin \left( 2\omega \cdot \frac{2\pi}{\omega} + 2\varphi \right) - \sin(2\varphi) \right) \right] = (\dots) \frac{1}{2} \\
&= \sin(4\pi + 2\varphi) - \sin(2\varphi) = \sin(2\varphi) \cos(4\pi) - \sin(2\varphi) \\
&= \sin(4\pi) \cos(2\varphi) + \sin(2\varphi) \cos(4\pi) - \sin(2\varphi) = 0
\end{aligned}$$

$$\therefore \langle E_c \rangle = \frac{1}{2} \frac{1}{2} m \frac{F_0^2 \omega^2}{m^2} A^2(\omega) \cdot \frac{1}{2} \Rightarrow \boxed{\langle E_c \rangle = \frac{1}{4} \frac{F_0^2 \omega^2}{m} A^2(\omega)}$$

$$\langle E_p \rangle = \frac{1}{2} m \omega_0^2 \frac{F_0^2}{m^2} A^2 \langle \cos^2(\omega t + \varphi) \rangle$$

$$\boxed{\langle E_p \rangle = \frac{1}{4} \frac{F_0^2 \omega_0^2}{m} A^2}$$

(d) para  $\omega = \omega_0$ :  $\langle E_c \rangle = \langle E_p \rangle$

$$E_T(t) = E_c(t) + E_p(t)$$

$$\begin{aligned}
E_T(t) &= \frac{1}{2} \frac{F_0^2 \omega^2}{m} A^2 \sin^2(\omega t + \varphi) \\
&+ \frac{1}{2} \frac{1}{2} \omega_0^2 \frac{F_0^2}{m} A^2 \cos^2(\omega t + \varphi)
\end{aligned}$$

$$\boxed{E_T(t, \omega = \omega_0) = \frac{1}{2} \frac{F_0^2 \omega_0^2}{m} A^2}$$

$$E_T(t) = \frac{1}{2} \frac{F_0^2 \omega^2 A^2}{m} \sin^2(\omega t + \varphi) + \frac{1}{2} \frac{F_0^2 \omega_0^2 A^2}{m} \cos^2(\omega t + \varphi) \quad \text{L2 (2)}$$

$$\frac{d}{dt} E_T(t) = \frac{1}{2} \frac{F_0^2 \omega^2 A^2}{m} [2\omega \sin(\omega t + \varphi) \cos(\omega t + \varphi)] + \frac{1}{2} \frac{F_0^2 \omega_0^2 A^2}{m} [2\omega_0 \sin(\omega t + \varphi) \cos(\omega t + \varphi)]$$

$$\frac{d}{dt} E_T(t) = \frac{1}{2} \frac{F_0 \omega^2 A^2}{m} 2\omega \sin(\omega t + \varphi) \cos(\omega t + \varphi) (\omega^2 - \omega_0^2)$$

Para  $E_T(t)$  ser constante no tempo:  $\frac{d}{dt} E_T(t) = 0$

$$\therefore \frac{d}{dt} E_T(t) = 0 \Rightarrow \boxed{\omega = \omega_0}$$

(10)

$$(a) \quad W = - \int_c \vec{F} \cdot d\vec{r} = - \int_{x_0}^{x_1} -b v(t) dx = \int_{t_0}^{t_1} b v^2(t) dt$$

$\left\langle \frac{dx}{dt} = v(t) \right\rangle$

$$\therefore \boxed{\frac{dW}{dt} = b v^2(t)}$$

(b)  $x = A \cos(\omega t - \varphi)$ ,  $\dot{x} = -A \omega \sin(\omega t - \varphi)$

$$\langle P \rangle = \left\langle \frac{dW}{dt} \right\rangle = \frac{1}{T} \int_0^T b A^2 \omega^2 \sin^2(\omega t - \varphi) dt \Rightarrow \boxed{\langle P \rangle = \frac{b \omega^2 A^2}{2}}$$

(c)  $A^2 = \frac{F_0^2 / m^2}{(\omega_0^2 - \omega^2)^2 + (2\gamma\omega)^2}$ ,  $Q = \frac{\omega_0}{2\gamma}$ ,  $2\gamma = b/m$

$$\therefore \langle P \rangle = \frac{b \omega^2}{2} \frac{(2\gamma F_0 / m)^2}{[(\omega_0^2 - \omega^2)^2 + (2\gamma\omega)^2]}$$

$$\omega_0^2 = k/m, \quad z\gamma = b/m, \quad Q = \omega_0 / z\gamma$$

$$\langle P \rangle = \frac{\omega^2}{z} (z\gamma) \frac{F_0^2 / m}{\omega_0^2 \left[ \left( \frac{\omega_0}{\omega} - \frac{\omega}{\omega_0} \right)^2 + \frac{1}{Q^2} \right]} = \frac{F_0^2}{m} \frac{\gamma}{k} \frac{1}{\left[ \left( \frac{\omega_0}{\omega} - \frac{\omega}{\omega_0} \right)^2 + \frac{1}{Q^2} \right]}$$

$$\langle P \rangle = \frac{F_0^2}{k} \frac{\omega_0}{2Q} \frac{1}{\left[ \left( \frac{\omega_0}{\omega} - \frac{\omega}{\omega_0} \right)^2 + \frac{1}{Q^2} \right]}$$

$$\langle P \rangle = \frac{F_0^2 \omega_0}{2kQ} \frac{1}{\left[ \left( \frac{\omega_0}{\omega} - \frac{\omega}{\omega_0} \right)^2 + \frac{1}{Q^2} \right]}$$

$m = 0,2 \text{ kg}$        $F_0 = 2 \text{ N}$        $\omega_0^2 = \frac{k}{m}$   
 $b = 4 \frac{\text{Ns}}{\text{m}}$        $\omega = 30 \text{ s}^{-1}$   
 $k = 80 \text{ N/m}$        $F = F_0 \cos(\omega t)$        $z\gamma = \frac{b}{m}$

(a)  $\ddot{x} + z\gamma \dot{x} + \omega_0^2 x = \frac{F_0}{m} \cos(\omega t)$

$x(t) = A(\omega) \cos(\omega t + \phi)$ ,       $A(\omega) = \frac{F_0}{m} \frac{1}{\left[ (\omega_0^2 - \omega^2)^2 + (z\gamma\omega)^2 \right]^{1/2}}$   
 $\tan \phi = \frac{\omega z\gamma \omega^2}{\omega_0^2 - \omega^2}$

$\therefore A(\omega=30) = \frac{2}{0,2} \frac{1}{\left[ \left( \frac{80}{0,2} - 900 \right)^2 + \left( \frac{4}{0,2} \cdot 30 \right)^2 \right]^{1/2}} \Rightarrow \boxed{A(30) = 0,0128 \text{ m}}$

$\phi = \tan^{-1} \left( \frac{\frac{4}{0,2} \cdot 30}{-500} \right) = -50^\circ \text{ ou } 130^\circ$

(b)

$$W = - \int b v dx = - \int b v^2 dt, \quad v = -A\omega \sin(\omega t - \delta)$$

$$W = - \int_0^T b \cdot A^2 \omega^2 \sin^2(\omega t - \delta) dt = -b A^2 \omega^2 \int_0^T \sin^2(\omega t - \delta) dt$$

$$W = -b A^2 \omega^2 \left[ \frac{1}{2} T - \frac{1}{4\omega} \left[ \sin\left(2\omega \cdot \frac{2\pi}{\omega} - 2\delta\right) + \sin(2\delta) \right] \right]$$

$$W = -\frac{b A^2 \omega^2 T}{2} \Rightarrow W = -\frac{b A^2 \omega^2 \cdot \frac{2\pi}{\omega}}{2} \Rightarrow \boxed{W = -\pi b A^2 \omega}$$

$$\boxed{W = 0,062 \text{ J}}$$

(c)

$$P(t) = \frac{dW}{dt} = F_{\text{ext}} \frac{dx}{dt} = \frac{F_0}{m} \cos(\omega t) \cdot [-A\omega \sin(\omega t - \delta)]$$

$$\langle P \rangle = -\frac{1}{T} \int_0^T \frac{F_0}{m} A\omega \cos(\omega t) \sin(\omega t - \delta) dt = -\frac{F_0 A\omega}{4\pi} [-\sin \delta (2\pi)]$$

$$\therefore \boxed{\langle P \rangle = \frac{F_0 A\omega}{2} \sin \delta = 0,29 \text{ W}}$$

$$\textcircled{13} \quad \frac{d}{dt} \langle P \rangle = 0 \Rightarrow \omega = \omega_0 \Rightarrow \langle P_{\text{max}} \rangle = \frac{1}{2} \frac{F_0^2 \omega_0 Q}{k}$$

$$\textcircled{a} \quad \omega_0 = 40 \text{ s}^{-1}$$

$$2f_0 = 2 \cdot 10 \text{ s}^{-1} \Rightarrow \boxed{Q = 20}$$

$$(b) \quad x(t) = A e^{-\gamma t} \cos(\omega t + \phi)$$

$$\dot{x}(t) = -\gamma A e^{-\gamma t} \cos(\omega t + \phi) + A e^{-\gamma t} \omega \sin(\omega t + \phi)$$

$$E_T(t) = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} k x^2 = \frac{1}{2} m A^2 e^{-2\gamma t} \left[ \cos(\omega t + \phi) \gamma - \omega \sin(\omega t + \phi) \right]^2$$

$$+ \frac{1}{2} \omega^2 m A^2 e^{-2\gamma t} \sin^2(\omega t + \phi) \quad , \quad T = \frac{2\pi}{\omega_0}$$

$$\frac{E_T(t=0)}{E(nT)} = e^5 = \frac{\frac{1}{2} m A^2 (\gamma \cos \phi - \omega \sin \phi)^2 - \frac{1}{2} m \omega_0^2 \omega^2 A^2 \sin^2 \phi}{\dots}$$

(...)

$$5 - 2\gamma\pi n / \omega$$

$$e^5 = 1 \Rightarrow 5 - \frac{2\pi n}{\omega} \gamma = 0$$

$$\text{como } \omega \approx \omega_0: \quad 5 = \frac{2\pi n}{\omega_0} \gamma \Rightarrow n = \frac{5\omega_0}{2\pi \gamma}$$

$$\boxed{n = 16 \text{ ciclos}}$$

$$\omega_1 \rightarrow \omega$$

$$\omega_0 \rightarrow \omega_1$$

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$$(a) \quad \omega_1 = \sqrt{\omega_0^2 - 2\gamma^2}$$

$$\text{metade pot} \Rightarrow 2\gamma = \omega_1 / 5$$

$$\text{pot max} = \omega_0$$

$$\omega_1^2 = \omega_0^2 - \frac{\omega_1^2}{10}$$

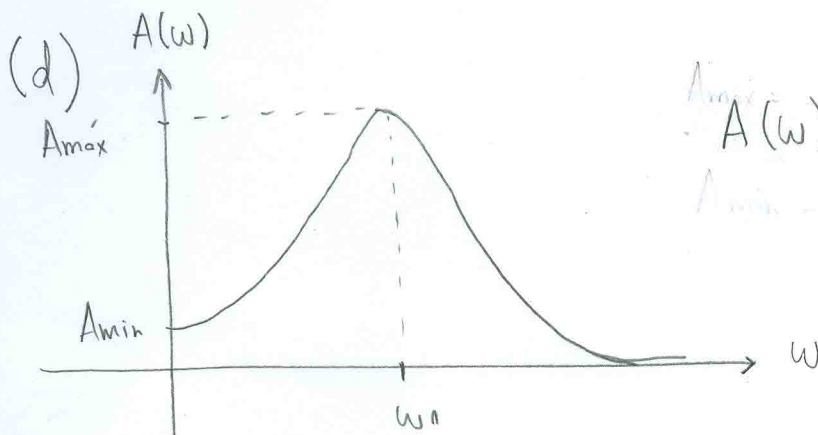
$$\boxed{\omega_0 = \omega_1 \frac{\sqrt{101}}{10}}$$

$$(b) Q = \frac{\omega_0}{2\gamma} = \frac{\omega_1 \sqrt{101}/10}{\omega_1/5} \Rightarrow \boxed{Q = \frac{\sqrt{101}}{2}}$$

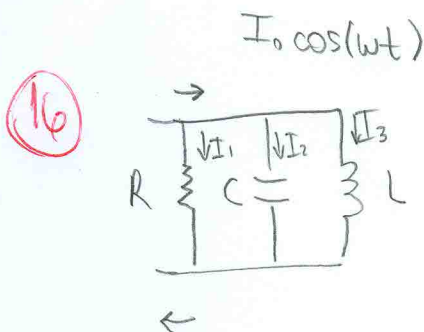
L2④

$$(c) 2\gamma = \frac{b}{m} \Rightarrow b = 2\gamma m = \frac{\omega_1 m}{5}$$

$$b = \frac{m}{5} \cdot \frac{10}{\sqrt{101}} \omega_0 = \frac{m}{5} \cdot \frac{10}{\sqrt{101}} \sqrt{\frac{K}{m}} \Rightarrow \boxed{b = \frac{2\sqrt{Km}}{\sqrt{101}}}$$



$$A(\omega) = \frac{F_0}{m} \frac{1}{[(\omega_0^2 - \omega^2)^2 + (2\gamma\omega)^2]^{1/2}}$$



$$V_R = I_1 R \quad (1)$$

$$I = I_1 + I_2 + I_3$$

$$V_C = L \frac{q_2}{C} \quad (2)$$

$$I = I_0 \cos(\omega t)$$

$$V_L = L \frac{dI_3}{dt} \quad (3)$$

$$(1) \text{ e } (2) : I_1 R = L \frac{dI_3}{dt} \Rightarrow I_1 = \frac{L}{R} \frac{dI_3}{dt}$$

$$(2) \text{ e } (3) : \frac{q_2}{C} = L \frac{dI_3}{dt} \Rightarrow q_2 = LC \frac{dI_3}{dt} \Rightarrow I_2 = \frac{dq_2}{dt}$$

$$\left( \frac{L}{R} \frac{dI_3}{dt} + LC \frac{d^2 I_3}{dt^2} + I_3 = I_0 \cos(\omega t) \right) \begin{cases} \omega_0 = \sqrt{1/CL} \\ 2\gamma = 1/RC \end{cases}$$

$$\langle P_{\max} \rangle = \langle P(\omega_0) \rangle$$

$$\langle P_{\max} \rangle = \frac{1}{2} \frac{F_0^2 \omega_0^2 Q^2}{k} = \frac{F_0^2 Q^2}{2m \omega_0} = \frac{F_0^2 \omega_0^2 \omega_0^2}{2m \omega_0^2 \gamma} = \frac{F_0^2}{2m \gamma}$$

$$\therefore \langle P_{\max} \rangle = \frac{1}{2} I_0 \frac{\omega_0^2}{\gamma} \Rightarrow \langle P_{\max} \rangle = \frac{I_0^2}{2} \cdot \frac{R}{L}$$

